

Genus and other graph invariants

Jinko Kanno

Louisiana Tech University

the 26th Cumberland, May 24-26, 2013

Outline

- 1 Introduction
- 2 Motivation
- 3 Our preliminary results
- 4 Problems

Surfaces

A **surface** is a connected compact 2-manifold without boundary.

- A *sphere*, a *torus*, a *projective plane*, or a *Klein bottle* is a surface. The plane can be considered as a punctured sphere.
- We have two types of closed surfaces, either **orientable** or **non-orientable**.

Surfaces

A **surface** is a connected compact 2-manifold without boundary.

- A *sphere*, a *torus*, a *projective plane*, or a *Klein bottle* is a surface. The plane can be considered as a punctured sphere.
- We have two types of closed surfaces, either **orientable** or **non-orientable**.

Surfaces

A **surface** is a connected compact 2-manifold without boundary.

- A *sphere*, a *torus*, a *projective plane*, or a *Klein bottle* is a surface. The plane can be considered as a punctured sphere.
- We have two types of closed surfaces, either **orientable** or **non-orientable**.

Surfaces

The classification theorem:

- The orientable surface S_g ($g \geq 0$) can be obtained from a sphere with $2g$ pairwise disjoint holes attached with g tubes (handles) such that each tube welds two holes.
- The number g is called the **genus** of the orientable surface.
- A sphere (the plane) = S_0 , and a torus = S_1 .

Surfaces

The classification theorem:

- The orientable surface S_g ($g \geq 0$) can be obtained from a sphere with $2g$ pairwise disjoint holes attached with g tubes (handles) such that each tube welds two holes.
- The number g is called the **genus** of the orientable surface.
- A sphere (the plane) = S_0 , and a torus = S_1 .

Surfaces

The classification theorem:

- The non-orientable surface N_k can be obtained from a sphere with k pairwise disjoint holes attached with k Möbius strips such that each Möbius strip welds one hole.
- The number k is called the **non-orientable genus** of N_k .
- A projective plane = N_1 , and a Klein bottle = N_2 .

Surfaces

The classification theorem:

- The non-orientable surface N_k can be obtained from a sphere with k pairwise disjoint holes attached with k Möbius strips such that each Möbius strip welds one hole.
- The number k is called the **non-orientable genus** of N_k .
- A projective plane = N_1 , and a Klein bottle = N_2 .

Genus of graphs

- A graph is **embeddable** into a surface if we can draw the graph on the surface without edge-crossing.
- The **genus** of a graph G , denoted $\gamma(G)$, is the *minimum* g of S_g into which G is embeddable.
- A graph G is **planar** iff $\gamma(G) = 0$.

Genus of graphs

- Similarly, the **non-orientable genus** of a graph G , denoted $\bar{\gamma}(G)$, is the minimum k of N_k into which G is embeddable.
- A graph G is *projective-planar* iff $\bar{\gamma}(G) = 1$.

Genus of graphs

- Similarly, the **non-orientable genus** of a graph G , denoted $\bar{\gamma}(G)$, is the minimum k of N_k into which G is embeddable.
- A graph G is *projective-planar* iff $\bar{\gamma}(G) = 1$.

Motivation

Only planar graphs ($\gamma = 0$) and projective planar graphs ($\bar{\gamma} = 1$) have been characterized by using minimal non-embeddable graphs (also called *excluded minor minimals* or *obstructions*).

The minimal non-embeddable graphs for torus ($\gamma = 1$) is unknown (more than 16,000).

Motivation

- *Contracting a non-loop edge e* is to delete e and then to identify the endpoints of e .
- A graph H is a *minor* of G if H can be obtained from a subgraph of G by contracting an edge repeatedly.
- We say that G *contains H -minor* if G contains a minor isomorphic to H .

Motivation

- *Contracting a non-loop edge e* is to delete e and then to identify the endpoints of e .
- A graph H is a *minor* of G if H can be obtained from a subgraph of G by contracting an edge repeatedly.
- We say that G *contains H -minor* if G contains a minor isomorphic to H .

Motivation

- *Contracting a non-loop edge e* is to delete e and then to identify the endpoints of e .
- A graph H is a *minor* of G if H can be obtained from a subgraph of G by contracting an edge repeatedly.
- We say that G *contains H -minor* if G contains a minor isomorphic to H .

Motivation

Known results

- A graph G is planar ($\gamma = 0$)
 $\iff G$ is K_5 - and $K_{3,3}$ -minor-free.
- G is $K_{3,3}$ -minor-free toroidal ($\gamma = 1$)
 $\iff G$ is F_i -minor-free with $1 \leq i \leq 4$.
(F_1 and F_2 are 0-sum and 1-sum of two K_5 's, respectively.)

Motivation

Known results

- A graph G is planar ($\gamma = 0$)
 $\iff G$ is K_5 - and $K_{3,3}$ -minor-free.
- G is $K_{3,3}$ -minor-free toroidal ($\gamma = 1$)
 $\iff G$ is F_i -minor-free with $1 \leq i \leq 4$.
(F_1 and F_2 are 0-sum and 1-sum of two K_5 's, respectively.)

Motivation

- There are several methods to be considered to characterize genus of graphs.
 1. Use H -minor-free graphs for some small graphs H .
 2. Combine with other graph invariants: thickness, outerthickness or else?
- Later we introduce a graph-surface invariant.

Motivation

- There are several methods to be considered to characterize genus of graphs.
 1. Use H -minor-free graphs for some small graphs H .
 2. Combine with other graph invariants: thickness, outerthickness or else?
- Later we introduce a graph-surface invariant.

Motivation

- Edge-decomposition into forests (forest thickness) has been solved completely (Nash-Williams, 1964). It was called **arboricity**.

The **thickness** of a graph G , denoted $\Theta(G)$, is a minimum number of layers required for G to be decomposed into planar subgraphs.

Motivation

A graph G is **outerplanar** if and only if G is embeddable in the plane in such a way that all vertices of G are on the boundary of the outer-face.

The **outerthickness** of G , denoted $\Theta_o(G)$, is the minimum number of layers required to make an edge-decomposition into outerplanar subgraphs.

Motivation

A graph G is **outerplanar** if and only if G is embeddable in the plane in such a way that all vertices of G are on the boundary of the outer-face.

The **outerthickness** of G , denoted $\Theta_o(G)$, is the minimum number of layers required to make an edge-decomposition into outerplanar subgraphs.

Motivation

- In 2005, Daniel Gonçalves proved every planar graph can be decomposed to at most two outerplanar subgraphs.
 - Let $\mathcal{O}(t)$ be the class of all graphs with outerthickness at most t .
 - Every planar graph is in $\mathcal{O}(2)$.
 - For every graph G , $\Theta_o(G) \leq 2\Theta(G)$.

Motivation

- In 2005, Daniel Gonçalves proved every planar graph can be decomposed to at most two outerplanar subgraphs.
 - Let $\mathcal{O}(t)$ be the class of all graphs with outerthickness at most t .
 - Every planar graph is in $\mathcal{O}(2)$.
 - For every graph G , $\Theta_o(G) \leq 2\Theta(G)$.

Motivation

- In 2005, Daniel Gonçalves proved every planar graph can be decomposed to at most two outerplanar subgraphs.
 - Let $\mathcal{O}(t)$ be the class of all graphs with outerthickness at most t .
 - Every planar graph is in $\mathcal{O}(2)$.
 - For every graph G , $\Theta_o(G) \leq 2\Theta(G)$.

Motivation

- In 2005, Daniel Gonçalves proved every planar graph can be decomposed to at most two outerplanar subgraphs.
 - Let $\mathcal{O}(t)$ be the class of all graphs with outerthickness at most t .
 - Every planar graph is in $\mathcal{O}(2)$.
 - For every graph G , $\Theta_o(G) \leq 2\Theta(G)$.

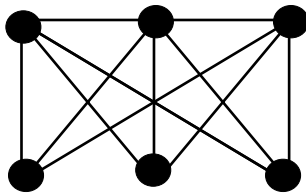
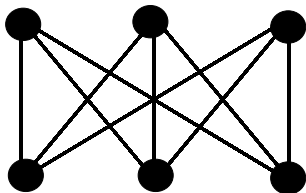
Our preliminary results

- In other words, the class of K_5 -minor-free and $K_{3,3}$ -minor-free graphs is in $\mathcal{O}(2)$.
- We were interested in seeing how larger class of this kind, such as $K_{3,n}$ -minor-free graphs, falls in $\mathcal{O}(2)$.

Our preliminary results

- In other words, the class of K_5 -minor-free and $K_{3,3}$ -minor-free graphs is in $\mathcal{O}(2)$.
- We were interested in seeing how larger class of this kind, such as $K_{3,n}$ -minor-free graphs, falls in $\mathcal{O}(2)$.

$K_{3,3}$ and $K_{3,3}^{++}$



If $K_{3,3}$ -free, then $K_{3,3}^{++}$ -free.

Our preliminary results

- The class of $K_{3,3}^{++}$ -minor free graphs is in $\mathcal{O}(2)$.
- If $K_{3,3}$ -free, then $K_{3,3}^{++}$ -free.
- Therefore, the class of $K_{3,3}$ -minor free graphs is in $\mathcal{O}(2)$.

Our preliminary results

- The class of $K_{3,3}^{++}$ -minor free graphs is in $\mathcal{O}(2)$.
- If $K_{3,3}$ -free, then $K_{3,3}^{++}$ -free.
- Therefore, the class of $K_{3,3}$ -minor free graphs is in $\mathcal{O}(2)$.

Our preliminary results

- The class of $K_{3,3}^{++}$ -minor free graphs is in $\mathcal{O}(2)$.
- If $K_{3,3}$ -free, then $K_{3,3}^{++}$ -free.
- Therefore, the class of $K_{3,3}$ -minor free graphs is in $\mathcal{O}(2)$.

Our preliminary results

- The class of K_5 -minor free graphs is not in $\mathcal{O}(2)$ since $\Theta_o(K_{3,9}) = 3$. We determined the following.
 - The class of K_5 -minor free and $K_{3,4}$ -minor free graphs is in $\mathcal{O}(2)$.
 - But, the class of K_5 -minor free and $K_{3,5}$ -minor free graphs is not in $\mathcal{O}(2)$. We construct a counterexample.

Our preliminary results

- The class of K_5 -minor free graphs is not in $\mathcal{O}(2)$ since $\Theta_o(K_{3,9}) = 3$. We determined the following.
 - The class of K_5 -minor free and $K_{3,4}$ -minor free graphs is in $\mathcal{O}(2)$.
 - But, the class of K_5 -minor free and $K_{3,5}$ -minor free graphs is not in $\mathcal{O}(2)$. We construct a counterexample.

Our preliminary results

- The class of K_5 -minor free graphs is not in $\mathcal{O}(2)$ since $\Theta_o(K_{3,9}) = 3$. We determined the following.
 - The class of K_5 -minor free and $K_{3,4}$ -minor free graphs is in $\mathcal{O}(2)$.
 - But, the class of K_5 -minor free and $K_{3,5}$ -minor free graphs is not in $\mathcal{O}(2)$. We construct a counterexample.

A new graph-surface invariant

- Let S be a surface $S_g (g > 0)$ or $N_k (k > 1)$. Suppose G is embeddable in S .
- We define a new graph-surface invariant, denoted $\mathbf{st}(G, S)$.
- Let **e-curves** on S be disjoint simple closed noncontractable curves. The standard **meridian** on a torus is an e-curve.

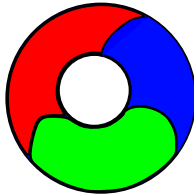
A new graph-surface invariant

- Let S be a surface $S_g (g > 0)$ or $N_k (k > 1)$. Suppose G is embeddable in S .
- We define a new graph-surface invariant, denoted **st(G,S)**.
- Let **e-curves** on S be disjoint simple closed noncontractable curves. The standard **meridian** on a torus is an e-curve.

A new graph-surface invariant

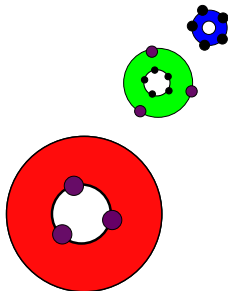
- Let S be a surface $S_g (g > 0)$ or $N_k (k > 1)$. Suppose G is embeddable in S .
- We define a new graph-surface invariant, denoted $\mathbf{st}(\mathbf{G}, \mathbf{S})$.
- Let **e-curves** on S be disjoint simple closed noncontractable curves. The standard **meridian** on a torus is an e-curve.

3 meridians on a torus



The torus consists of blue, green and red cylinders.

3 cylinders and vertices



Vertices on the 3 cylinders are appropriately identified.

A new graph-surface invariant

- Among all embeddings of G into S , let $st(G, S)$ be the minimum number of e-curves on S such that the curves pass through all vertices without crossing any edges of G .
- If G is toroidal, then $st(G, S_1)$ is called the **meridian number** of G .

A new graph-surface invariant

- Among all embeddings of G into S , let $st(G, S)$ be the minimum number of e-curves on S such that the curves pass through all vertices without crossing any edges of G .
- If G is toroidal, then $st(G, S_1)$ is called the **meridian number** of G .

A new graph-surface invariant

- Imagine a graph G is embedded in a surface and a set of e-curves of G is known.
- If we cut the surface through the e-curves of G , then we obtain h_i -holed disks that $V(G)$ are on the boundaries of the disks and no edge crossings on each disk (a new way to visualize embedded graph).

A new graph-surface invariant

- Imagine a graph G is embedded in a surface and a set of e -curves of G is known.
- If we cut the surface through the e -curves of G , then we obtain h_i -holed disks that $V(G)$ are on the boundaries of the disks and no edge crossings on each disk (a new way to visualize embedded graph).

A new graph-surface invariant

Advantages of the $st(G, S)$.

- Let $\mathcal{ST}(S, t)$ be the set of graphs G embeddable in S with $st(G, S) \leq t$. Then $\mathcal{ST}(S, t)$ is **topological-minor-closed**. Not minor-closed because contracting an edge whose endpoints are on different e-curves makes the e-curves intersect.
- Provide a new way to visualize embedded graph. For example, K_7 has a symmetric presentation in S_1 . (no struggle!)

A new graph-surface invariant

Advantages of the $st(G, S)$.

- Let $\mathcal{ST}(S, t)$ be the set of graphs G embeddable in S with $st(G, S) \leq t$. Then $\mathcal{ST}(S, t)$ is **topological-minor-closed**. Not minor-closed because contracting an edge whose endpoints are on different e-curves makes the e-curves intersect.
- Provide a new way to visualize embedded graph. For example, K_7 has a symmetric presentation in S_1 . (no struggle!)

A new graph-surface invariant

The followings have meridian number 1.

- K_7 (David VanHeeswijk)
- $K_{4,4}$
- $K_{3,6}$
- $(K_5 - e) +_0 (K_5 - e)$
- $K_5 +_1 (K_5 - e)$

Stacey McAdams: $K_5 +_0 (K_5 - e)$ has meridian number at most 2.

A new graph-surface invariant

Conjecture (J.K.):

The toroidal graph obtained from p -fold covering space of (K_7, S_1) along the standard longitude of S_1 has meridian number p .

Remark: This is false for arbitrary graph. There exists a graph that its 3-fold covering space has meridian number 1.

A new graph-surface invariant

Conjecture (J.K.):

The toroidal graph obtained from p -fold covering space of (K_7, S_1) along the standard longitude of S_1 has meridian number p .

Remark: This is false for arbitrary graph. There exists a graph that its 3-fold covering space has meridian number 1.

Problems

Here are unsolved problems.

- Is every projective-planar graph in $\mathcal{O}(2)$?
- Let M be a $K_{3,4}$ -minor-free projective-planar graph (see John Maharry et al.)
Is every M in $\mathcal{O}(2)$?

Problems

Here are unsolved problems.

- Is every projective-planar graph in $\mathcal{O}(2)$?
- Let M be a $K_{3,4}$ -minor-free projective-planar graph (see John Maharry et al.)
Is every M in $\mathcal{O}(2)$?

Problems

Here are unsolved problems.

- Is every projective-planar graph in $\mathcal{O}(2)$?
- Let M be a $K_{3,4}$ -minor-free projective-planar graph (see John Maharry et al.)
Is every M in $\mathcal{O}(2)$?

Problems

- Find excluded minor minimals for each set of $\mathcal{ST}(\mathcal{S}_1, t)$.
- Find excluded topological minor minimals for each set of $\mathcal{ST}(\mathcal{S}_1, t)$.
- Classify the known excluded minor minimals G for toroidal by using a higher surface $st(G, N_k)$ or $st(G, S_g)$.

Problems

- Find excluded minor minimals for each set of $\mathcal{ST}(S_1, t)$.
- Find excluded topological minor minimals for each set of $\mathcal{ST}(S_1, t)$.
- Classify the known excluded minor minimals G for toroidal by using a higher surface $st(G, N_k)$ or $st(G, S_g)$.

Problems

- Find excluded minor minimals for each set of $\mathcal{ST}(S_1, t)$.
- Find excluded topological minor minimals for each set of $\mathcal{ST}(S_1, t)$.
- Classify the known excluded minor minimals G for toroidal by using a higher surface $st(G, N_k)$ or $st(G, S_g)$.

- If G is embeddable into both S_1 and N_2 , then how are $st(G, N_2)$ and $st(G, S_1)$ related?
- For example, is $st(G, N_2) > st(G, S_1)$ true for any G ?
- If $\gamma(G) = g$ and $st(G, S_g) > 1$, $st(G, S_{g+1}) = st(G, S_g) - 1$ is true?
- Characterize the relationship between $st(G, S)$ and $O_o(G)$.

- If G is embeddable into both S_1 and N_2 , then how are $st(G, N_2)$ and $st(G, S_1)$ related?
- For example, is $st(G, N_2) > st(G, S_1)$ true for any G ?
- If $\gamma(G) = g$ and $st(G, S_g) > 1$, $st(G, S_{g+1}) = st(G, S_g) - 1$ is true?
- Characterize the relationship between $st(G, S)$ and $O_o(G)$.

- If G is embeddable into both S_1 and N_2 , then how are $st(G, N_2)$ and $st(G, S_1)$ related?
- For example, is $st(G, N_2) > st(G, S_1)$ true for any G ?
- If $\gamma(G) = g$ and $st(G, S_g) > 1$, $st(G, S_{g+1}) = st(G, S_g) - 1$ is true?
- Characterize the relationship between $st(G, S)$ and $O_o(G)$.

Thank you!